

NACHI ROBOT

ISO 9001

SA Fast Series

SA100F/130F/160F/200F

(Spot welding, Material handling)

NACHI

No.1 Technology of Fast Series

The SA Fast Series features the fastest, a space-saving design, a large work envelope, low maintenance requirements, and improved repeatability. The compact, but powerful, SA Fast Series has a streamlined profile, reduced interference zones, and has a 36% smaller footprint than earlier models. The SA Fast Series also eliminates parallel linkage, resulting in space-saving robots and increased flexibility. Despite their reduced size, the SA Fast robots deliver more power and a larger work envelope than many conventional robots. Additionally, the SA Fast Series lowers maintenance needs through fewer grease points and longer-life components. The SA Fast robots reduce cable and hose wear by incorporating a built-in air hose, with built-in I/O connections, a water hose, and a primary welding cable optionally available. Finally, to ensure accuracy, the SA Fast Series has improved repeatability, from 0.5 to 0.3 millimeters.

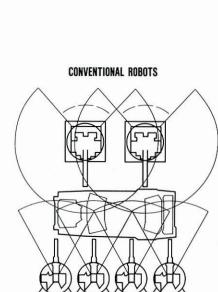
Innovative No.1 technology of Fast Series Features:

- ☐ The fastest robot

 35% speed up with feed-forward
 and vibration control
- Space-Saving Design
- ☐ Larger Working Envelope (1.9 times larger)
- ☐ Compact body
- ☐ Improved Accuracy (Repeatability of ±0.3mm)
- ☐ Fewer Grease Points
- ☐ Reduced Cable and Hose Wear by using Buit-in Air Hose, and Optional Built-in I/O Connections, Water Line, and Primary Welding Cable
- ☐ Small, High-Torque Wrist
- Larger 50kg. Load Capacity on Forearm
- ☐ Shelf-Mount Model Available

Robot Applications:

- Spot Welding
- Machine loading and Unloading
- ☐ Plasma Cutting
- Sealing





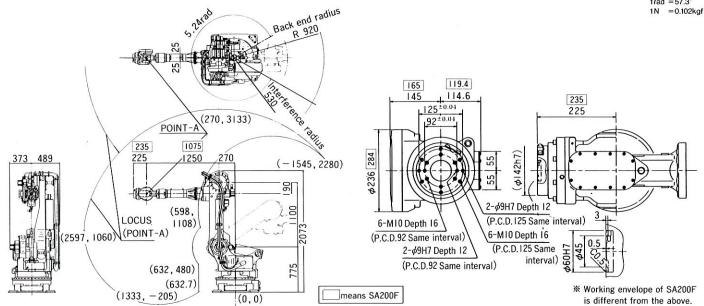


SA Fast Series SA100F/130F/160F/200F

■ Basic Specification

Item				Specification			
Robot Model				SA100F	SA130F	SA160F	SA200F
Construction				Articular	Articular	Articular	Articular
Number of Axis				6	6	6	6
Drive				AC servo motor	AC servo motor	AC servo motor	AC servo motor
Maximum Strike	Arm	S	Swivel	±2.62rad	±2.62rad	±2.62rad	±2.62rad
		Н	Back & Forth	+1.31~ -0.96rad	+1.31~ -0.96rad	+1.31~ -0.96rad	+1.31~-0.96rad
		V	Up & Down	+2.53~ -2.01rad	+2.53~ -2.01rad	+2.53~-2.01rad	+2.53~-2.01rad
	Wrist	R2	Rotation 2	±6.28rad	±6.28rad	±6.28rad	±6.28rad
		В	Bend	±2.18rad	±2.18rad	±2.18rad	±2.18rad
		R1	Rotation 1	±6.28rad	±6.28rad	±6.28rad	±6.28rad
Maximum Velocity	Arm	S	Swivel	2.09rad/s	2.09rad/s	1.75rad/s	1.22rad/s
		Н	Back & Forth	2.09rad/s	2.09rad/s	1.75rad/s	1.22rad/s
		V	Up & Down	2.09rad/s	2.09rad/s	1.75rad/s	1.22rad/s
	Wrist	R2	Rotation 2	2.79rad/s	2.79rad/s	2.18rad/s	1.75rad/s
		В	Bend	2.79rad/s	2.79rad/s	2.18rad/s	1.75rad/s
		R1	Rotation 1	4.28rad/s	4.28rad/s	3.49rad/s	2.62rad/s
Looding Woight			Wrist	100kg	130kg	160kg	200kg
Loading Weight		Foream		50kg	25kg	25kg	
Wrist Torque		R2	Rotation 2	559N·m	735N·m	882N∙m	1274N · m
		В	Bend	559N·m	735N·m	882N·m	1274N • m
		R1	Rotation 1	343N·m	392N·m	441N•m	686N+m
Repeatability				±0.3mm	±0.3mm	±0.3mm	±0.5mm
Ambient Temperature				0~45°C	0∼45°C	0~45°C	0~45°C
Installation				Floor	Floor	Floor	Floor
Robot Body Weight				1280kg	1280kg	1280kg	1330kg

1rad = 57.3°



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Caution